

365 (1): Lagrangian Analysis with Spin Corrections

In the non relativistic limit the Hamiltonian is:

$$H = \frac{1}{2} m \underline{\dot{r}} \cdot \underline{\dot{r}} + U(r) \quad (1)$$

and the Lagrangian is:

$$L = \frac{1}{2} m \underline{\dot{r}} \cdot \underline{\dot{r}} - U(r) \quad (2)$$

for a central potential. The three dimensional Euler Lagrange equation is:

$$\underline{\nabla} L = \frac{d}{dt} \frac{\partial L}{\partial \underline{\dot{r}}} \quad (3)$$

From eqs. (2) and (3):

$$\underline{F} = m \underline{\ddot{r}} = - \underline{\nabla} U \quad (4)$$

Eq. (4) is true in any coordinate system.

The relativistic Hamiltonian is:

$$H = mc^2 \left(1 - \frac{\underline{\dot{r}} \cdot \underline{\dot{r}}}{c^2} \right)^{-1/2} + U(r) \quad (5)$$

and the relativistic Lagrangian is:

$$L = -mc^2 \left(1 - \frac{\underline{\dot{r}} \cdot \underline{\dot{r}}}{c^2} \right)^{1/2} - U(r) \quad (6)$$

As shown in UFT 328, simultaneous solution of eqns. (5) and (6) gives a precessing orbit.

From eqs. (3) and (6):

$$\underline{F} = - \underline{\nabla} U = - \frac{d}{dt} \frac{\partial}{\partial \underline{\dot{r}}} \left(mc^2 \left(1 - \frac{\underline{\dot{r}} \cdot \underline{\dot{r}}}{c^2} \right)^{1/2} \right) \quad (7)$$

Denote

$$y = 1 - \frac{\dot{\underline{r}} \cdot \dot{\underline{r}}}{c^2} \quad (8)$$

then

$$\frac{dy}{d\dot{\underline{r}}} = -\frac{2\dot{\underline{r}}}{c^2} \quad (9)$$

Denote:

$$f = y^{1/2} \quad (10)$$

then

$$\frac{df}{dy} = \frac{1}{2} y^{-1/2} \quad (11)$$

so

$$\frac{df}{d\dot{\underline{r}}} = \frac{df}{dy} \frac{dy}{d\dot{\underline{r}}} = -\frac{2\dot{\underline{r}}}{c^2} \frac{1}{2} y^{-1/2} \quad (12)$$

$$= -\frac{\dot{\underline{r}}}{c^2} \left(1 - \frac{\dot{\underline{r}} \cdot \dot{\underline{r}}}{c^2} \right)^{-1/2}$$

It follows that

$$\frac{dL}{d\dot{\underline{r}}} = -m\dot{\underline{r}} \left(1 - \frac{\dot{\underline{r}} \cdot \dot{\underline{r}}}{c^2} \right)^{-1/2} \quad (13)$$

and that:

$$\begin{aligned} \underline{F} &= -m \frac{d}{dt} \left(\dot{\underline{r}} \left(1 - \frac{\dot{\underline{r}} \cdot \dot{\underline{r}}}{c^2} \right)^{-1/2} \right) \quad (14) \\ &= -\underline{\nabla} U \end{aligned}$$

In the non-relativistic limit:

$$\underline{F} = m \underline{\ddot{r}} = m \frac{d\underline{v}}{dt} = -\underline{\nabla} U \quad (15)$$

In plane polar coordinates:

$$\underline{a} = (\ddot{r} - r\dot{\theta}^2) \underline{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta}) \underline{e}_\theta \quad (16)$$

and

$$\underline{v} = \dot{r} \underline{e}_r + r\dot{\theta} \underline{e}_\theta \quad (17)$$

$$= \frac{d\underline{r}}{dt}$$

The above analysis depends on:

$$\underline{r} = \underline{r}(t), \quad \underline{v} = \underline{v}(t), \quad (18)$$

so in plane polar coordinates:

$$\underline{\dot{r}} = \underline{v} = \dot{r} \underline{e}_r + r\dot{\theta} \underline{e}_\theta. \quad (19)$$

It follows that:

$$H = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + U(r) \quad (20)$$

and the Lagrangian is:

$$\mathcal{L} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - U(r) \quad (21)$$

This analysis produces a static ellipse:

$$r = \frac{\alpha}{1 + \epsilon \cos \theta} \quad (22)$$

and the results:

$$\dot{\theta} = \frac{L}{mr^2} \quad (23)$$

and

$$r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0 \quad (24)$$

4) for any planar orbit. The force law for eq. (22) is

therefore:
$$\underline{F} = m(\ddot{r} - r\dot{\theta}^2)\underline{e}_r = -\nabla U \quad (25)$$

which is the 1689 Leibnitz equation. The centrifugal force is

$$\underline{F}_{\text{cent}} = -mr\dot{\theta}^2 \underline{e}_r \quad (26)$$

The gradient of a function in plane polar coordinates is:

$$\underline{\nabla} U = \frac{\partial U}{\partial r} \underline{e}_r + \frac{1}{r} \frac{\partial U}{\partial \theta} \underline{e}_\theta \quad (27)$$

so if
$$U = U(r) \quad (28)$$

then
$$\underline{F} = m(\ddot{r} - r\dot{\theta}^2)\underline{e}_r = -\frac{\partial U}{\partial r} \underline{e}_r \quad (28)$$

so
$$m(\ddot{r} - r\dot{\theta}^2) = -\frac{\partial U(r)}{\partial r} = F(r) \quad (29)$$

which can be transformed to the Binet equation:

$$F(r) = -\frac{L^2}{mr^3} \left(\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} \right) \quad (30)$$

Note carefully that the Binet equation (30) holds for any orbit in a plane, and is more general than a Newtonian analysis. It has not been assumed in Eqs. (29) and (30) that $U(r)$ is an inverse square law.

In UFT 36E3 it was shown that if the velocity is assumed to be:

$$\underline{v} = \underline{v}(t, r(t), \theta(t)) \quad - (31)$$

Then:

$$\underline{v} = \frac{D\underline{R}}{Dt} = \frac{\partial \underline{R}}{\partial t} + (\underline{v} \cdot \nabla) \underline{R} \quad - (32)$$

where \underline{R} is the position vector of a fluid element:

$$\underline{R} = \underline{R}(t, r(t), \theta(t)) \quad - (33)$$

and
$$v_r = (1 + \Omega'_{01}) \dot{r} + \Omega'_{02} \omega r \quad - (34)$$

$$v_\theta = \omega r = r \dot{\theta} \quad - (35)$$

where
$$\Omega'_{01} = \frac{\partial \Omega}{\partial r}, \quad \Omega'_{02} = \frac{1}{r} \frac{\partial \Omega}{\partial \theta} \quad - (36)$$

If it is assumed that:

$$\Omega'_{02} \sim 0 \quad - (37)$$

The Binet equation is changed to:

$$F(r) = -\frac{L^2}{mr^3} \left((1 + \Omega'_{01}) \frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} \right) \quad - (38)$$

Assume in this equation that:

$$F(r) = -\frac{mMG}{r^2} \quad - (39)$$

so
$$(1 + \Omega'_{01}) \frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = \frac{m^2 MG}{L^2} \quad - (40)$$

It is known that if:

6) $\Omega'_{01} = 0 \quad - (41)$

then: $\frac{m^2 MG}{L^2} = \frac{1}{\alpha} \quad - (42)$

where $r = \frac{\alpha}{1 + \epsilon \cos \theta} \quad - (43)$

when considering orbits in the solar system, in which precessions are very small, then:

$$(1 + \Omega'_{01}) \frac{d^2}{dt^2} \left(\frac{1}{r} \right) + \frac{1}{r} = \frac{1}{\alpha} \quad - (44)$$

This equation can be solved by computer to give r as a function of θ and Ω'_{01} .

Under the condition:

$$v(t) \rightarrow v(t, r(t), \theta(t)) \quad - (45)$$

the inverse square law (39) no longer gives the ellipse (43). This is because the value of Ω'_{01} is changed, and it has an effect on the orbit.

It is possible to find the value of Ω'_{01} needed for a precessing ellipse. In a first approximation:

$$\frac{1}{r} = \frac{1}{\alpha} (1 + \epsilon \cos(x\theta)) \quad - (46)$$

where $x = 1 - \frac{3MG}{c^2 \alpha} \quad - (47)$

So:
$$\frac{d}{dt} \left(\frac{1}{r} \right) = -\frac{x \epsilon \sin(x\theta)}{d} \quad - (48)$$

and
$$\frac{d^2}{dt^2} \left(\frac{1}{r} \right) = -\frac{x^2 \epsilon \cos(x\theta)}{d} \quad - (49)$$

From eqs. (44), (48) and (49): - (50)

$$-\left(1 + \Omega'_{01}\right) \frac{x^2 \epsilon \cos(x\theta)}{d} + \frac{1}{d} \left(1 + \epsilon \cos(x\theta)\right) = \frac{1}{d}$$

i.e.
$$\frac{\epsilon \cos(x\theta)}{d} \left(1 - x^2 (1 + \Omega'_{01})\right) = 0 \quad - (51)$$

so
$$\boxed{x^2 = \frac{1}{1 + \Omega'_{01}}} \quad - (52)$$

It follows that under the condition:

$$\boxed{\Omega'_{01} = \frac{1}{x^2} - 1 = \frac{\partial R}{\partial r}} \quad - (53)$$

the inverse square law (39) produces the function (43), which is a precessing ellipse

More accurately the precessing ellipse is:

$$r = \frac{d}{1 + \epsilon \cos(f(\theta))} \quad - (54)$$

where $f(\theta)$ is a function of θ . So $f(\theta)$ can be found in terms of Ω'_{01} and vice versa, using computer algebra.