

# 356(5): Particular Solution of Note 356(4)

If it is assumed that:

$$V_r = f(r), \quad V_\phi = f(\phi), \quad V_\theta = f(\theta) \quad - (1)$$

Then:

$$\frac{-e^2}{4\pi\epsilon_0 r^2} = x V_r \left( \frac{2}{r} + \frac{d}{dr} \right) V_r \quad - (2)$$

$$\frac{V_\phi}{r \sin \theta} \frac{\partial V_\phi}{\partial \phi} = 0 \quad - (3)$$

$$\frac{V_\theta}{r} \left( \frac{1 + \cos \theta}{\sin \theta} \right) \frac{\partial V_\theta}{\partial \theta} = 0 \quad - (4)$$

So:  $\frac{\partial V_\phi}{\partial \phi} = 0 \quad - (5)$

$$\frac{\partial V_\theta}{\partial \theta} = 0 \quad - (6)$$

and

$$\frac{-e^2}{4\pi\epsilon_0 r^2} = \frac{2x}{r} V_r^2 + x V_r \frac{\partial V_r}{\partial r} \quad - (7)$$

Eq. (7) is a non linear partial differential equation for  $V_r$ .

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